



Mid-term project presentation

Group 1

Course: CS580

Speakers: Daniel Mocanu, Valentin Le Lièvre

Overview

1. Reminder of previous presentation
2. Project presentation and related work
3. Underwater light Scattering
4. Underwater Spectral Rendering
5. Improvements proposal
6. Current project state
7. Team Roles

Reminder of previous presentation

Lecture topic : **Spectral rendering**

We covered :

- Intuitive idea of spectral rendering
- New rendering equation with included wavelength parameter :

$$L_o(x, \omega_o) = L_e(x, \omega_o) + \int_{\Omega} f_r(x, \omega_i, \omega_o) L_i(x, \omega_i) \cos \theta_i d\omega_i$$

- Where to use spectral rendering : water, clouds, prism ...
- Drawbacks of spectral rendering : slow to compute, not suited for real-time applications

Our project topic

Underwater spectral rendering



Related background

State of the art simulation (faking) of underwater rendering in games



Render normal object in normal
lighting conditions

Related background

State of the art simulation (faking) of underwater rendering in games



Add a fog effect on the object

Related background

State of the art simulation (faking) of underwater rendering in games



Add layer of blue color filter

Related background

If the object is further away, blur is more intense, and blue color is darker



Further away from the camera

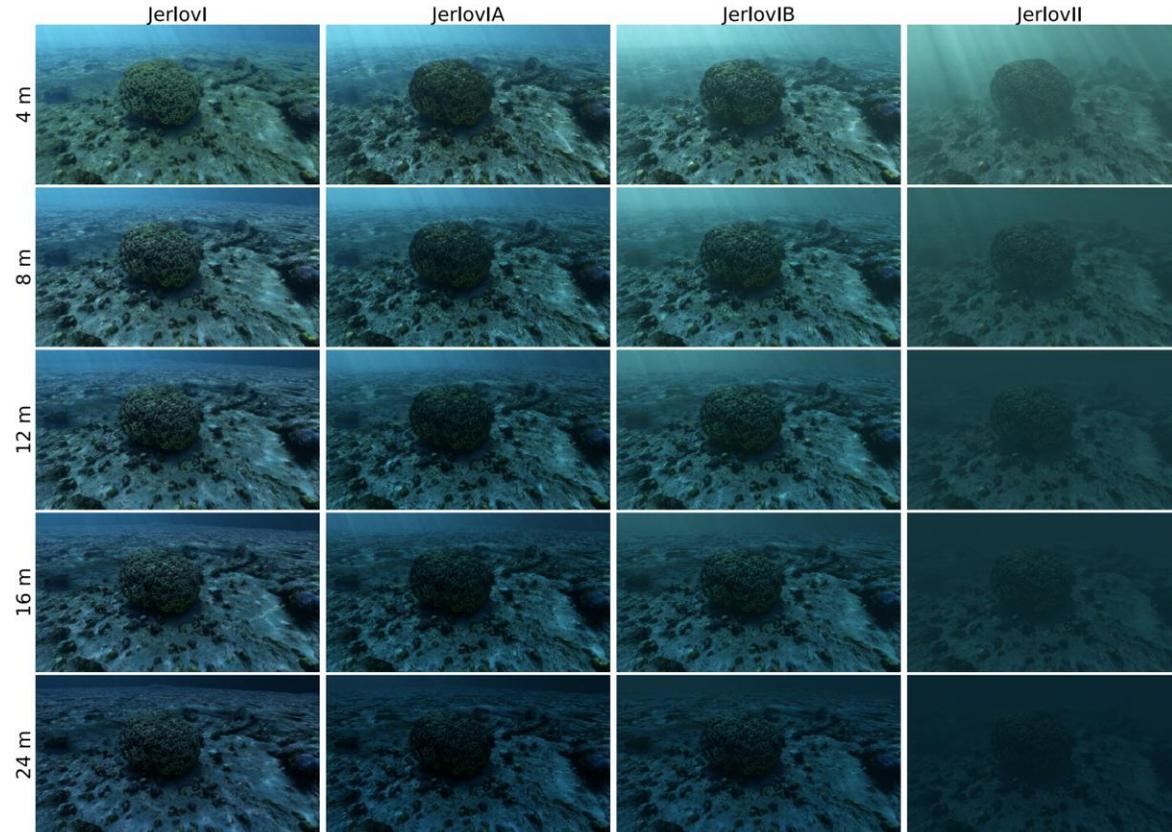


Related background



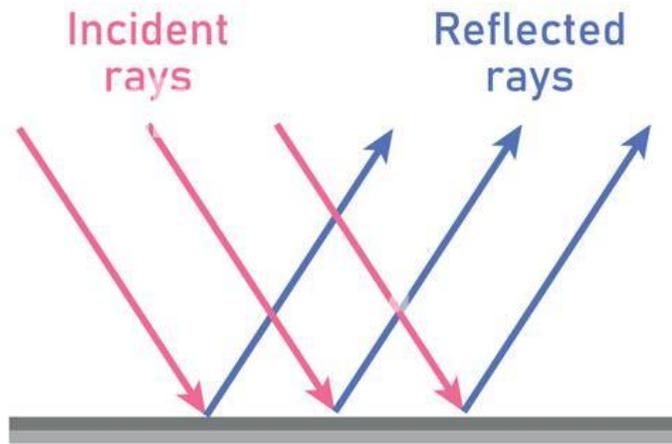
Rendering of Subnautica game using similar method

Related background

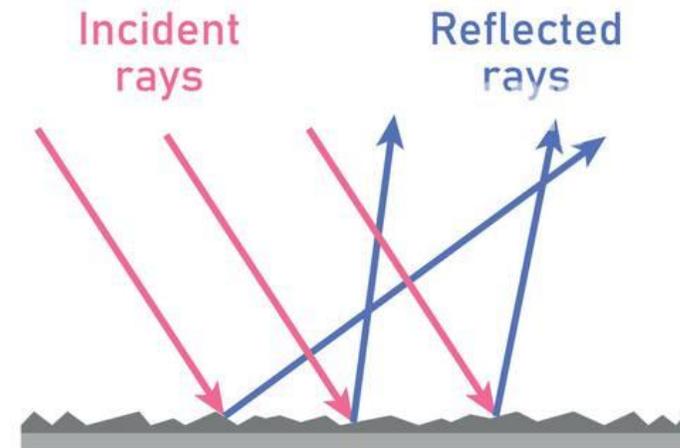


Comparison of multiple water types and depth with spectral rendering

Surface Light Scattering



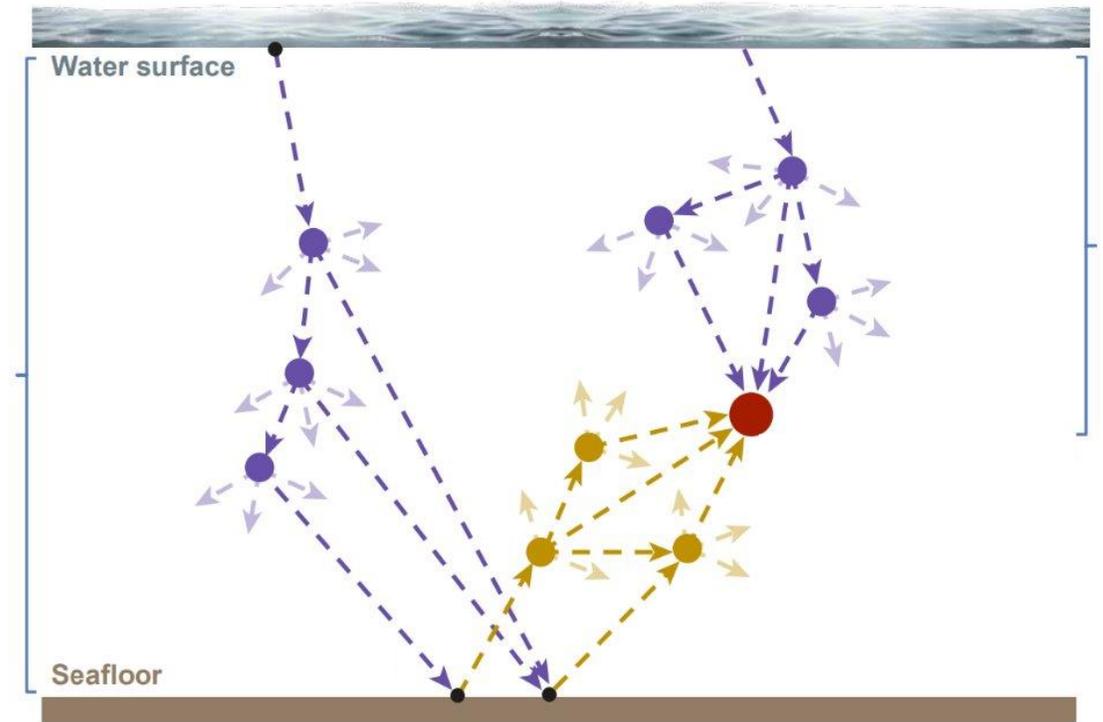
Regular Reflection



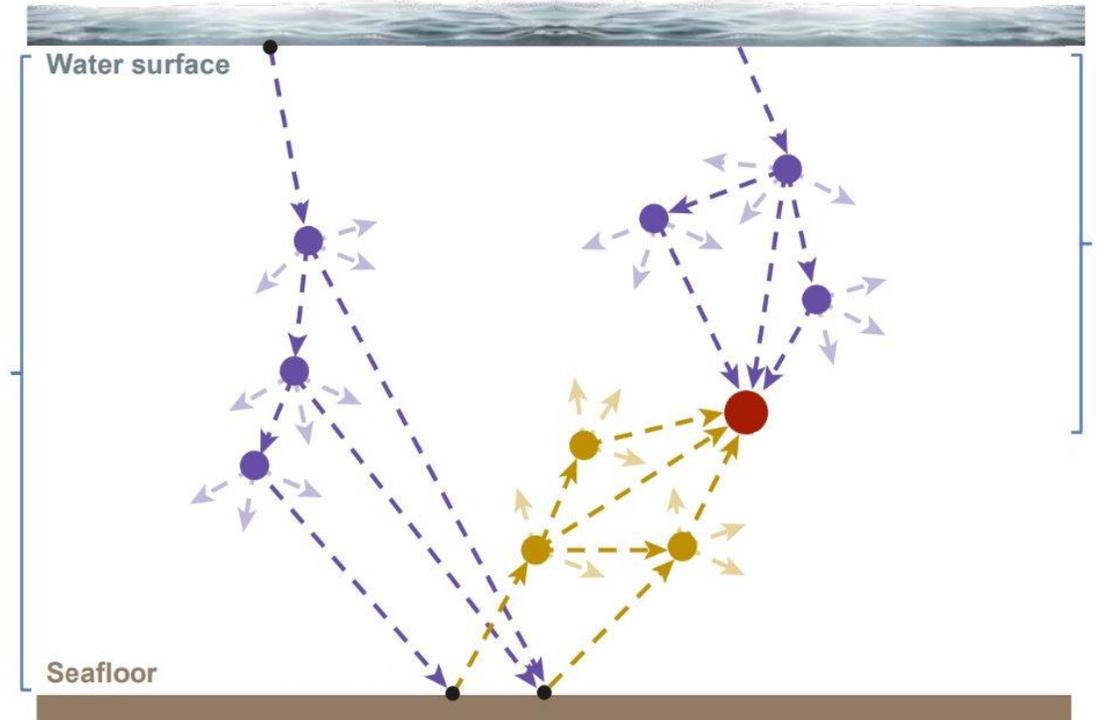
Diffuse Reflection

Underwater Light Behavior

- Water => (Formally) **Participation Medium**
- Scattering
- Absorption
- Short Wavelength (Blue)
- Long Wavelength (Red)



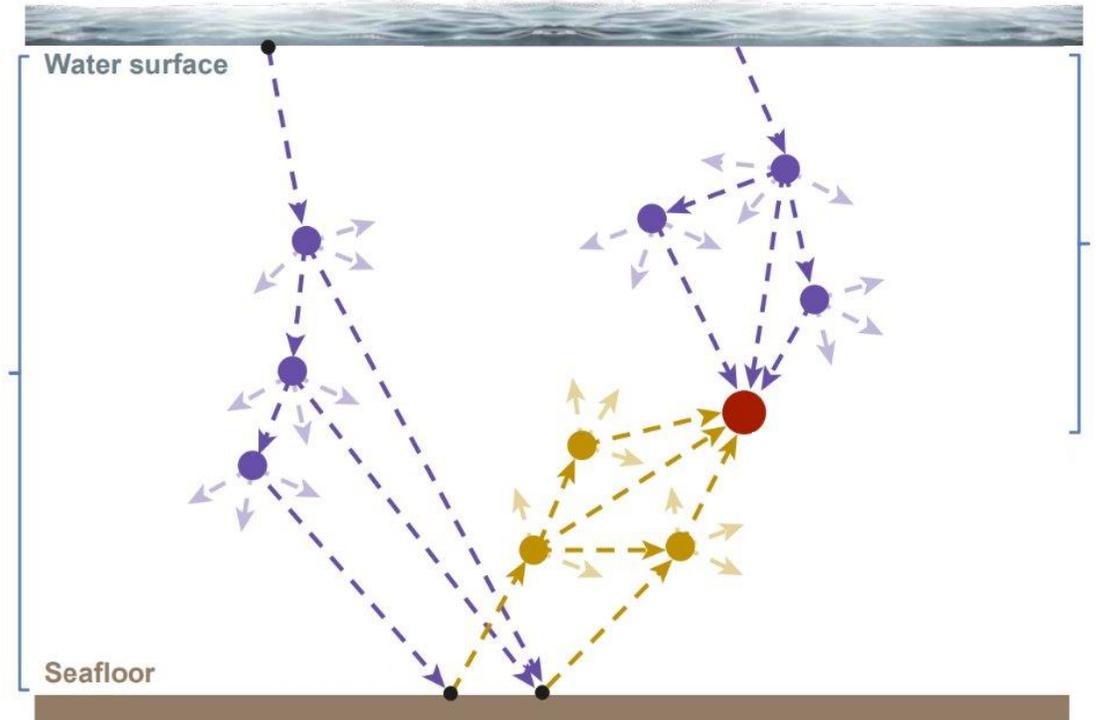
Underwater Light Behavior



Light Scattering and Absorption

- Scattering Coefficient δ_s - Probability of light being scattered per meter.
- $\delta_s L(x_z, \omega)$ - Differential scattered radiance.
- Absorption Coefficient δ_a - Probability of light being absorbed per meter.
- $\delta_a L(x_z, \omega)$ - Differential absorbed radiance.

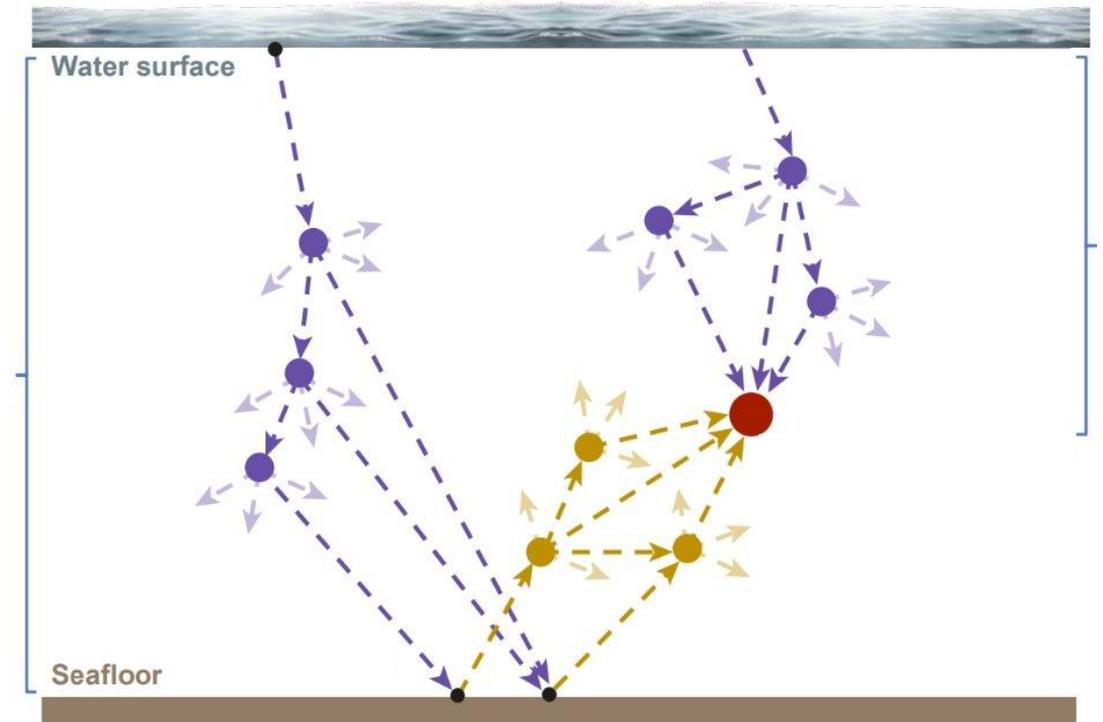
For a ray traveling in direction outgoing ω from position x .



Light Scattering and Absorption

- Extinction Coefficient: $\delta_t = \delta_a + \delta_s$ - Probability of absorption or scattering.
- $\frac{dL_{extinction}(x, \omega)}{dz} = -\delta_t L(x_z, \omega)$ - Differential Total Extinction

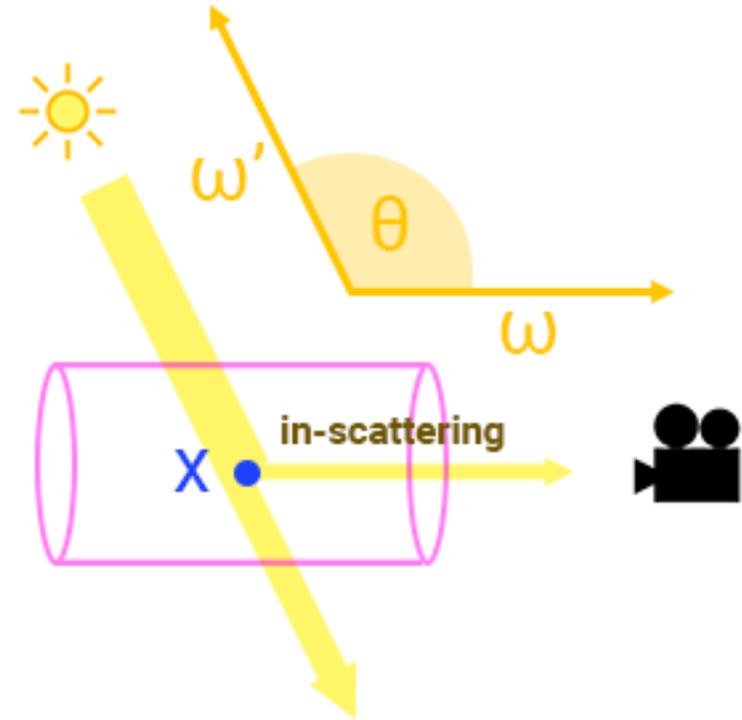
For a ray traveling in direction outgoing ω from position x .



Light In-scattering

- Incoming Incident Light from all directions.
- $\frac{dL_{in-scattering}(x,\omega)}{dz} = \delta_s L_i(x, \omega)$
- Where, $L_i(x, \omega) = \int_{\Omega} L(x, \omega_i) f_s(x, \omega_i, \omega) d\omega_i$
- $f_s(x, \omega_i, \omega)$ – Phase Function the likely-hood of scattering towards ω .

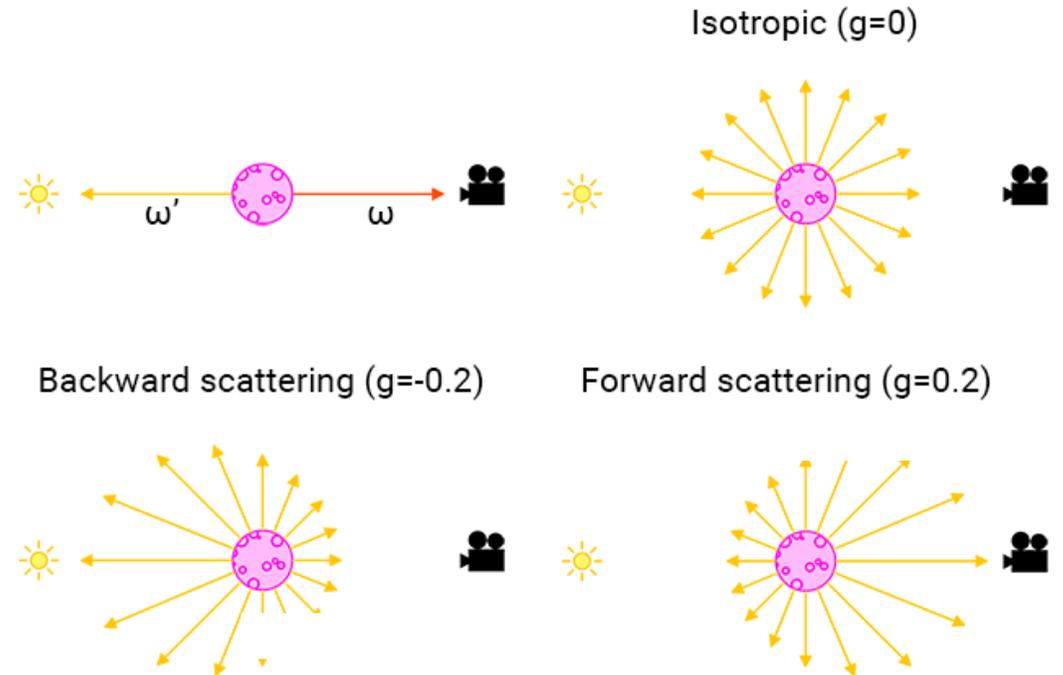
For a ray traveling in direction outgoing ω from position x .



Radiative Transfer Equation (RTE) in Water

- Differential Equation describing the amount of Radiance Gained.
- $$\frac{dL(x_z, \omega)}{dz} = \frac{dL_{\text{extinction}}(x, \omega)}{dz} + \frac{dL_{\text{in-scattering}}(x, \omega)}{dz}$$
- $$\frac{dL(x_z, \omega)}{dz} = -\delta_t L(x_z, \omega) + \int_{\Omega} L(x, \omega_i) f_s(x, \omega_i, \omega) d\omega_i$$

For a ray traveling in direction outgoing ω from position x .

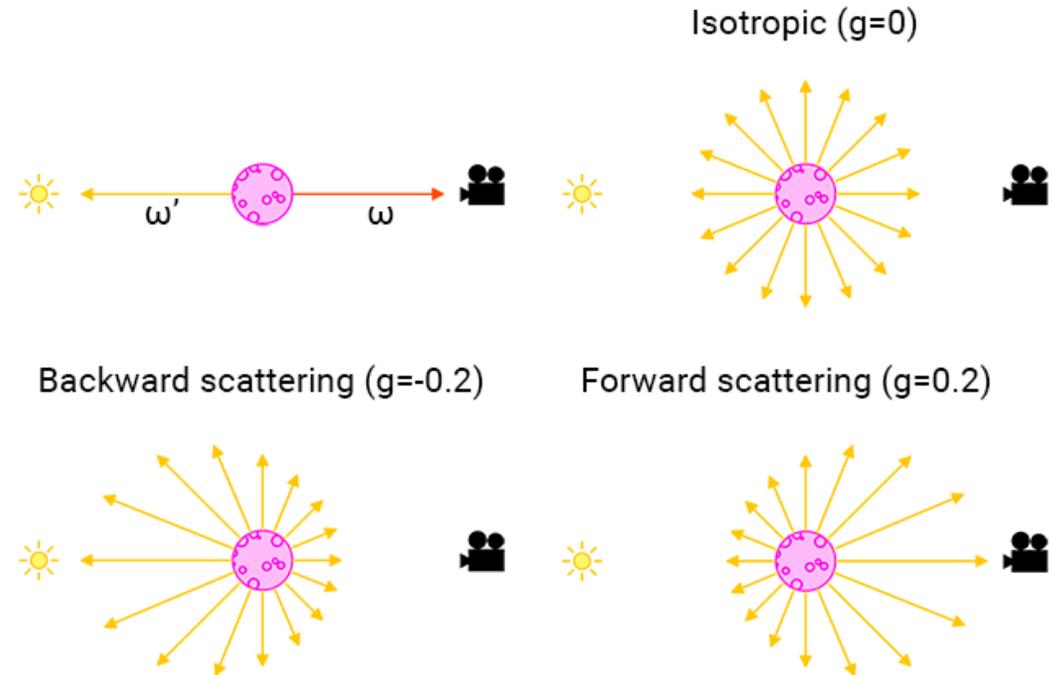


RTE in Participation Medium

- General RTE:

$$\frac{dL(x_z, \omega)}{dz} = -\delta_t L(x_z, \omega) + \int_{\Omega} L(x, \omega_i) f_s(x, \omega_i, \omega) d\omega_i + \delta_a L_e(x, \omega)$$

- Where: $\delta_a L_e(x, \omega)$ – Lighted emitted by the Participation Medium.
- For Non-Emissive Media (such as water) this term is equals 0.
- Emissive Media: Fire, Flames, Plasma etc.

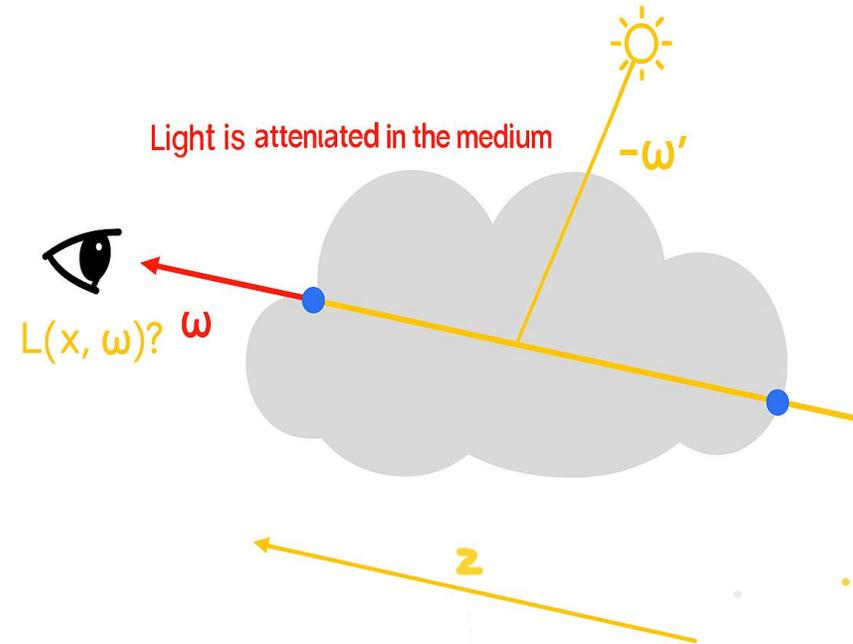


Volumetric Rendering Equation (VRE)

- RTE in water:

$$\frac{dL(x_z, \omega)}{dz} = -\delta_t L(x_z, \omega) + \int_{\Omega} L(x, \omega_i) f_s(x, \omega_i, \omega) d\omega_i$$

- Integrate over traveling distance Z.

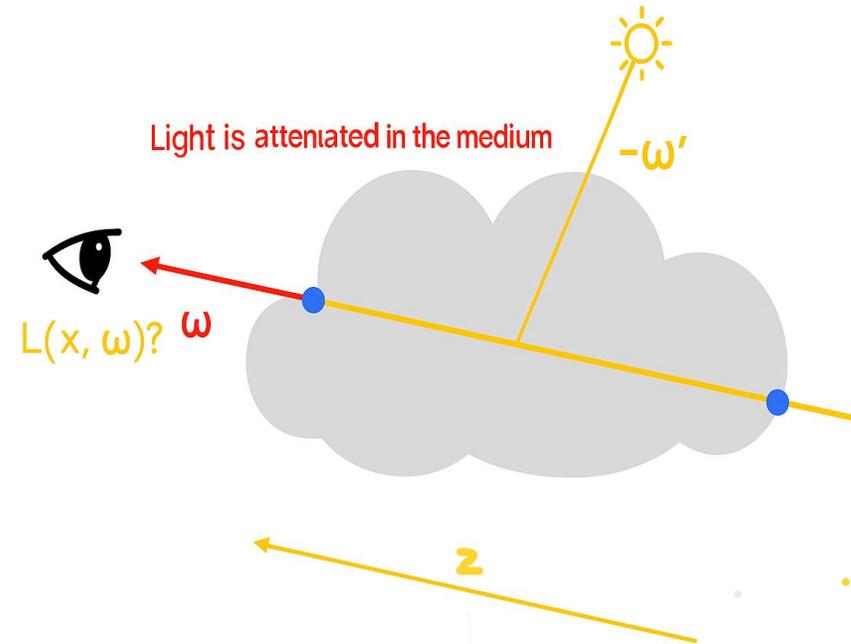


Volumetric Rendering Equation (VRE)

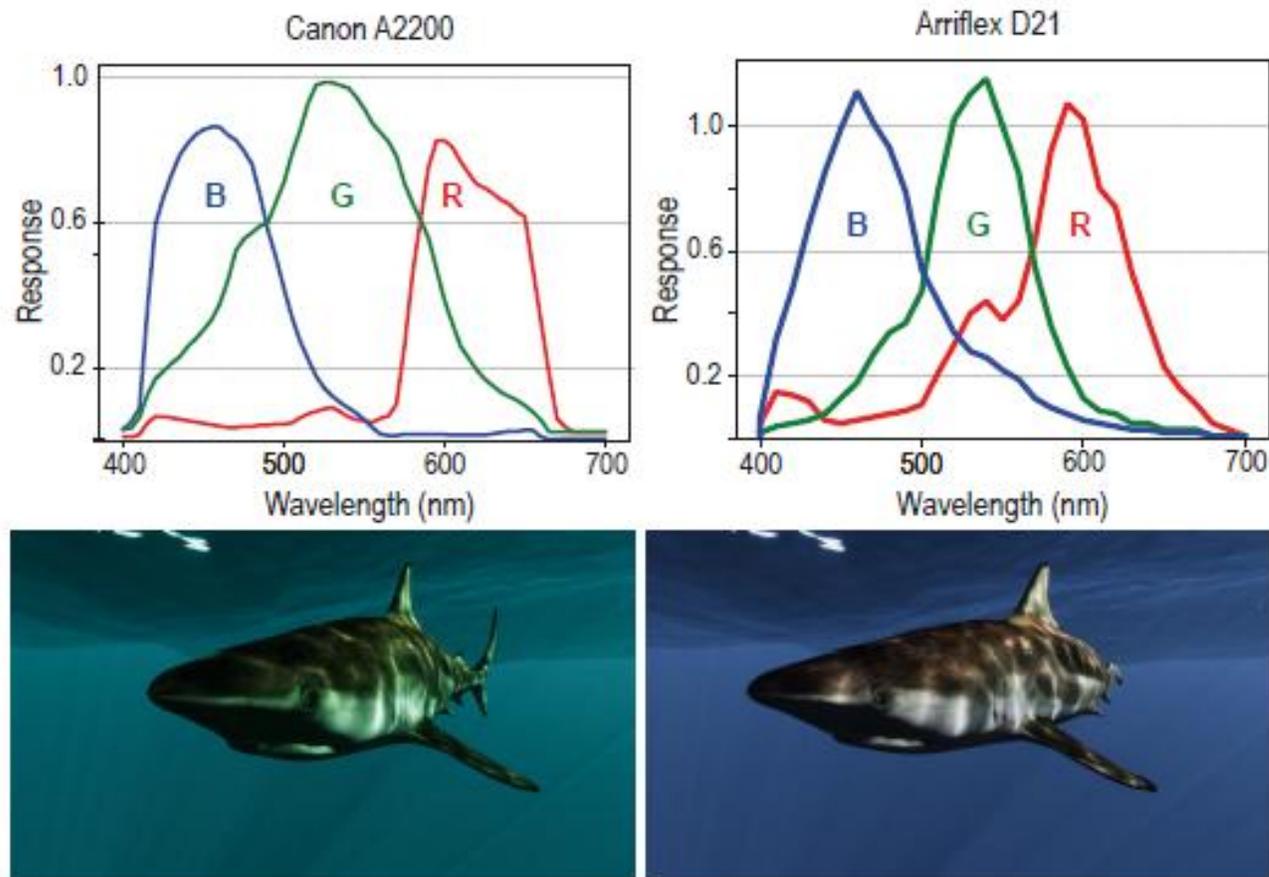
- VRE in water:

$$L(x_Z, \omega) = T(x_Z)L_S(x, \omega) + \int_{z=0}^Z T(x_Z) L_i(x_z, \omega) dz$$

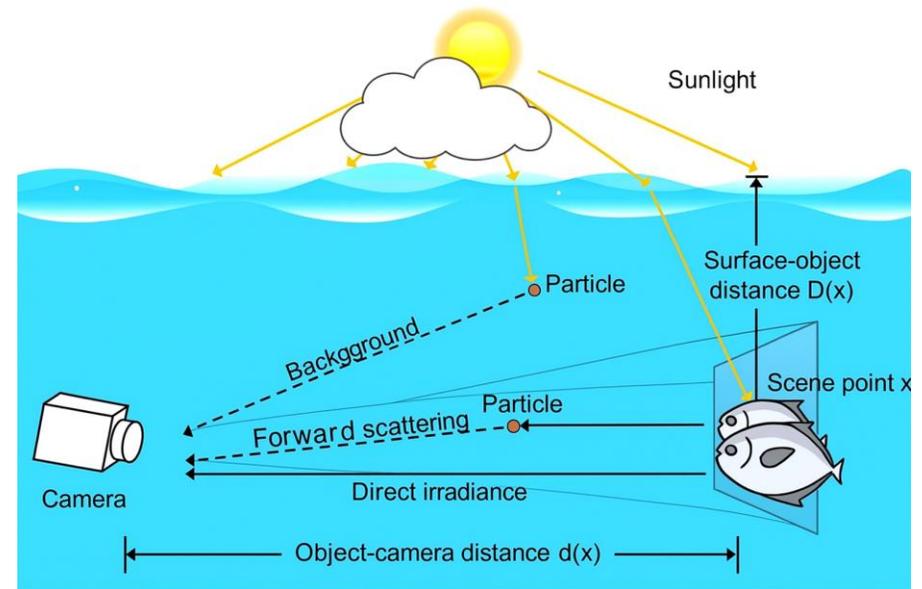
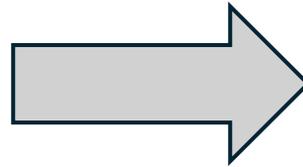
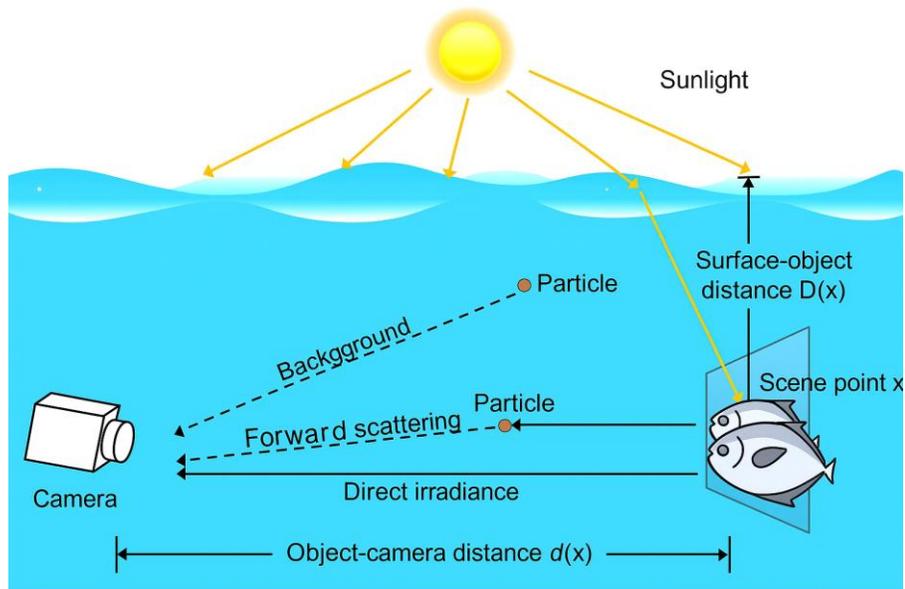
- Where, $L_i = \int_{\Omega} L(x, \omega_i) f_s(x, \omega_i, \omega) d\omega_i$;
- L_S - at the surface (or exit) point x_Z .
- $T(x_Z) = e^{-\sigma_t Z}$ - Transmittance of water over distance z ;



Proposal: Different Camera Sensors



Proposal: Non-Homogeneous Surface Light



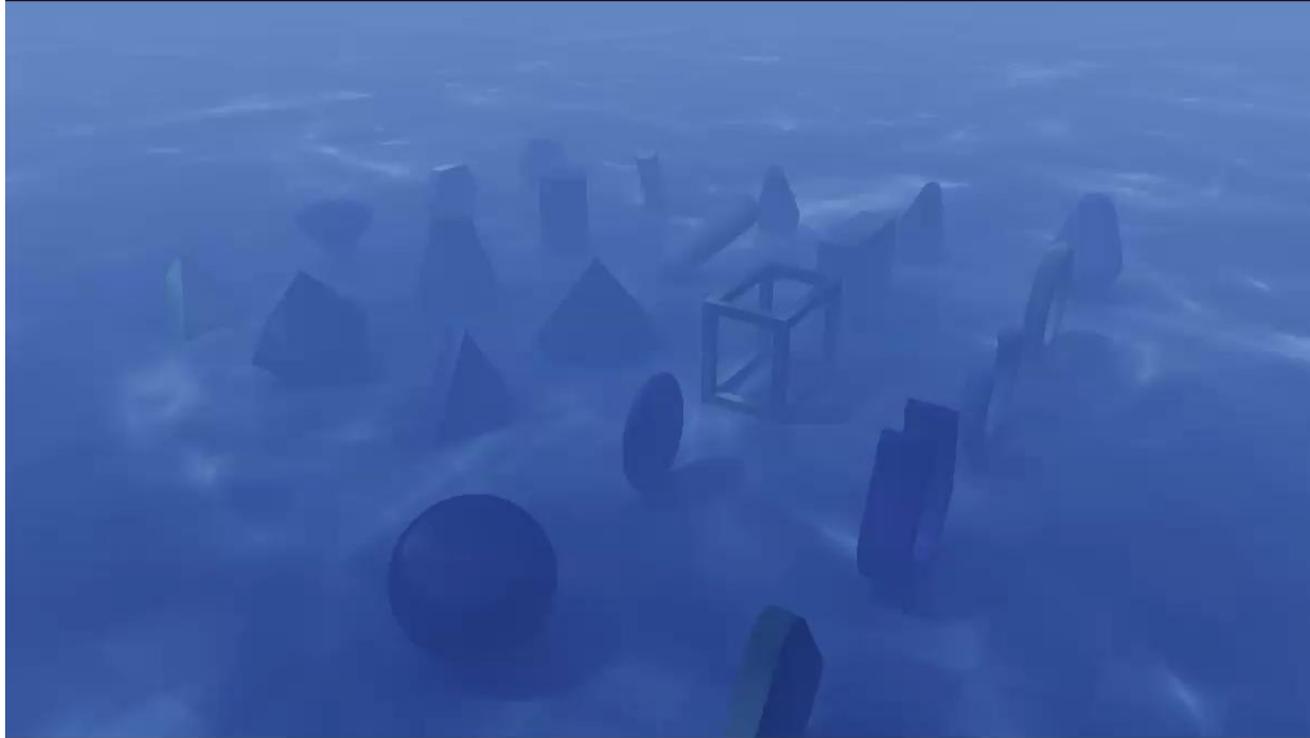
Current project state

Our paper had demo code we used to get started with

We are able to run the simple demo code and played with the settings to get some different results

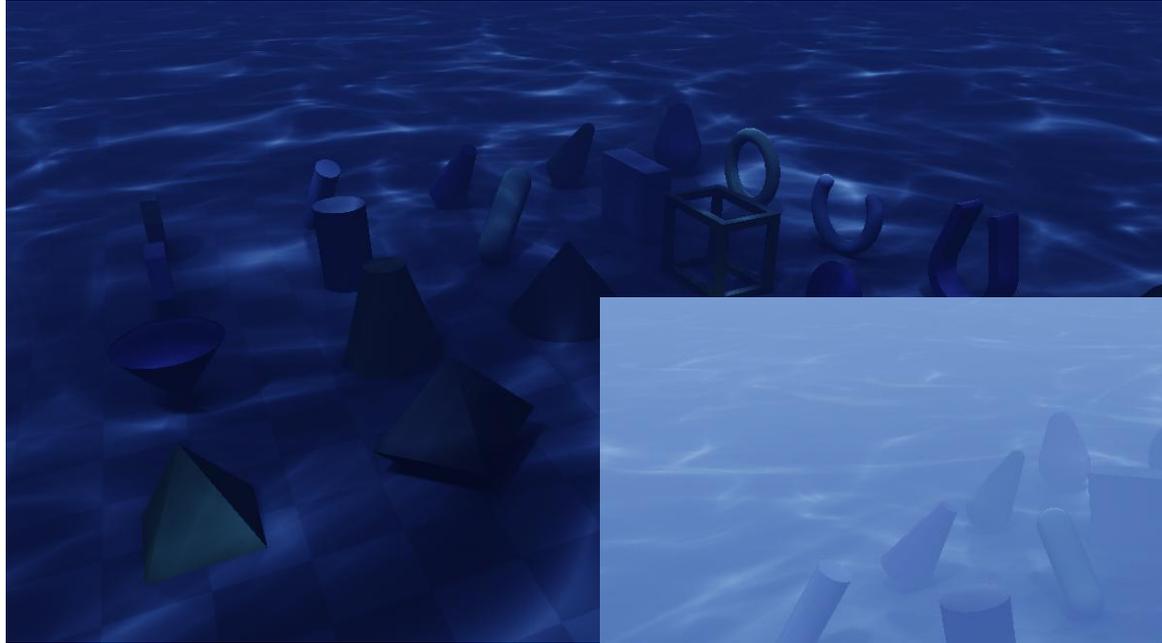
We started re-implementing the light equations of the paper to add our improvements we talked about

Current project state

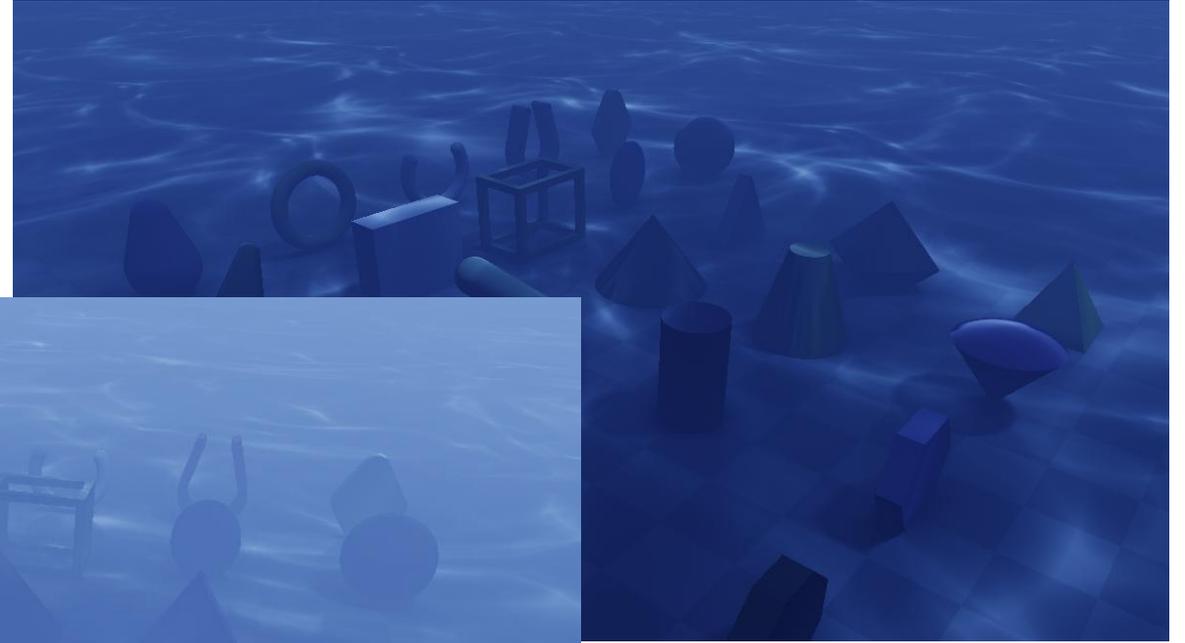


Demo code of our paper

Current project state



40m



30m



15m

Current project state

Different water types



Team work

Split the work evenly to both team member :

- Half the slides and presentation per team member
- Each read multiple related papers to gather ideas and related work

Daniel will focus more on the implementation of **non-homogeneous surface light**

Valentin will work on the implementation of **multiple camera sensors**

Thank you

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